

Ionospheric Tomography From The Owen's Valley LWA

Ryan Monroe

Advisor: Gregg Hallinan

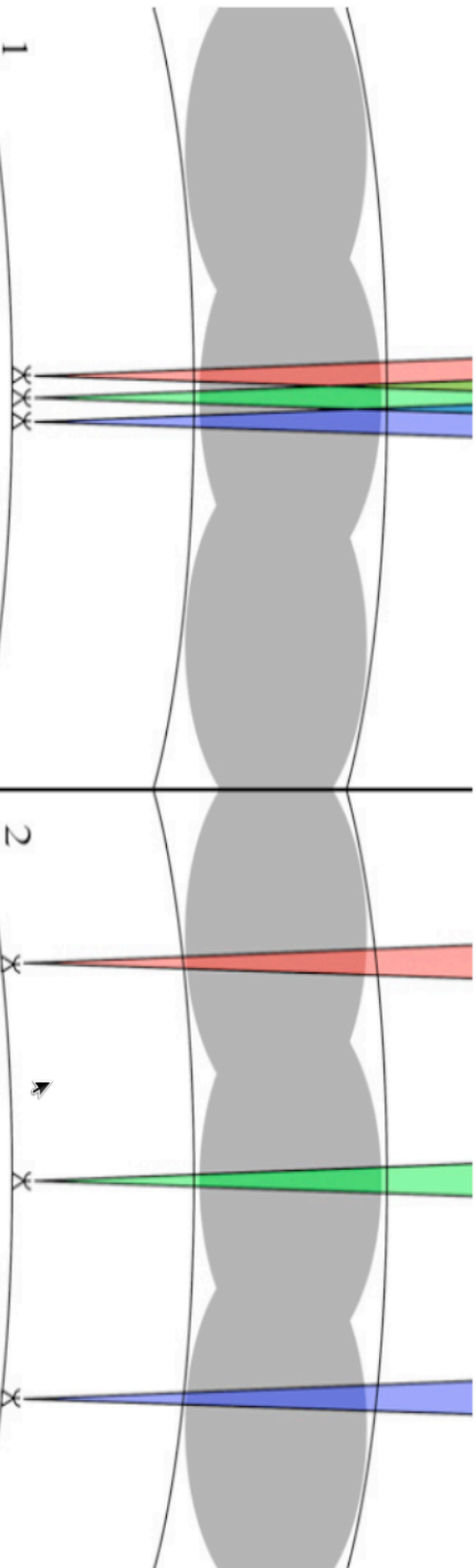


The big picture

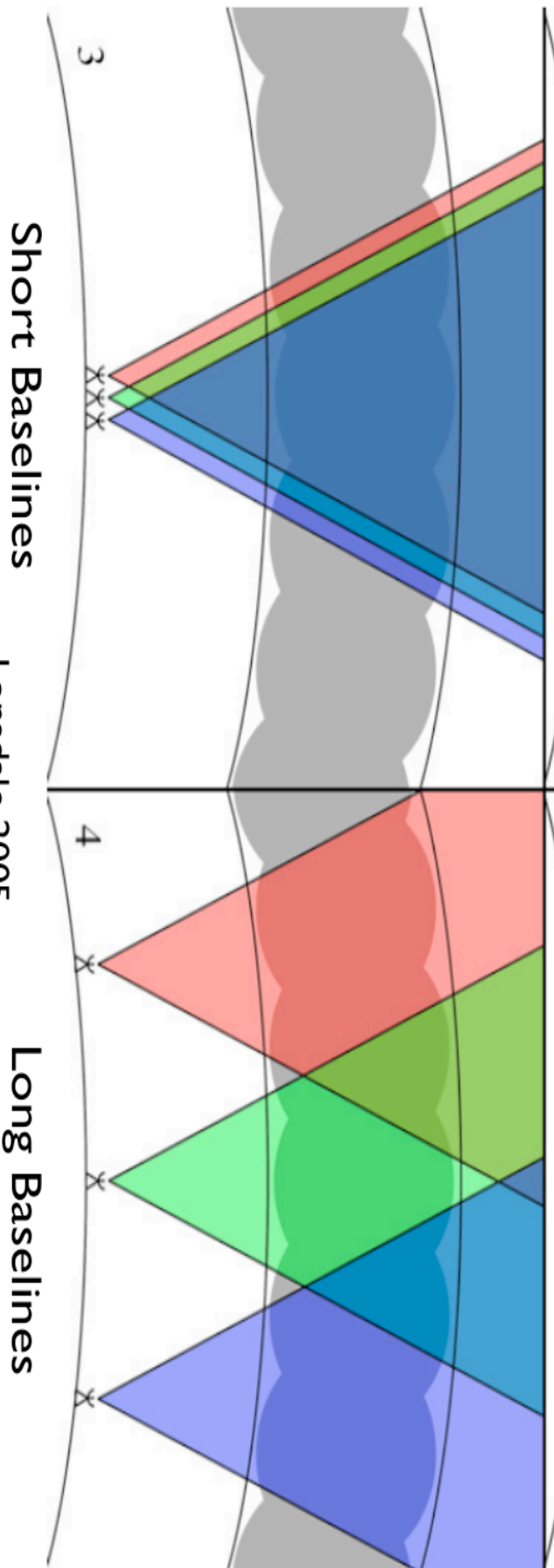
- Ionosphere: a layer of earth's atmosphere
- ~200-1500 km altitude
- Corrupts LWA images
 - Reflection
 - Refraction
 - Absorption
 - Scintillation
- Need some way to calibrate past

LWA-OVRO: Compact; large FOV

Small
FoV



Large
FoV



Short Baselines

Lonsdale 2005

Intema et al. 2009

Long Baselines

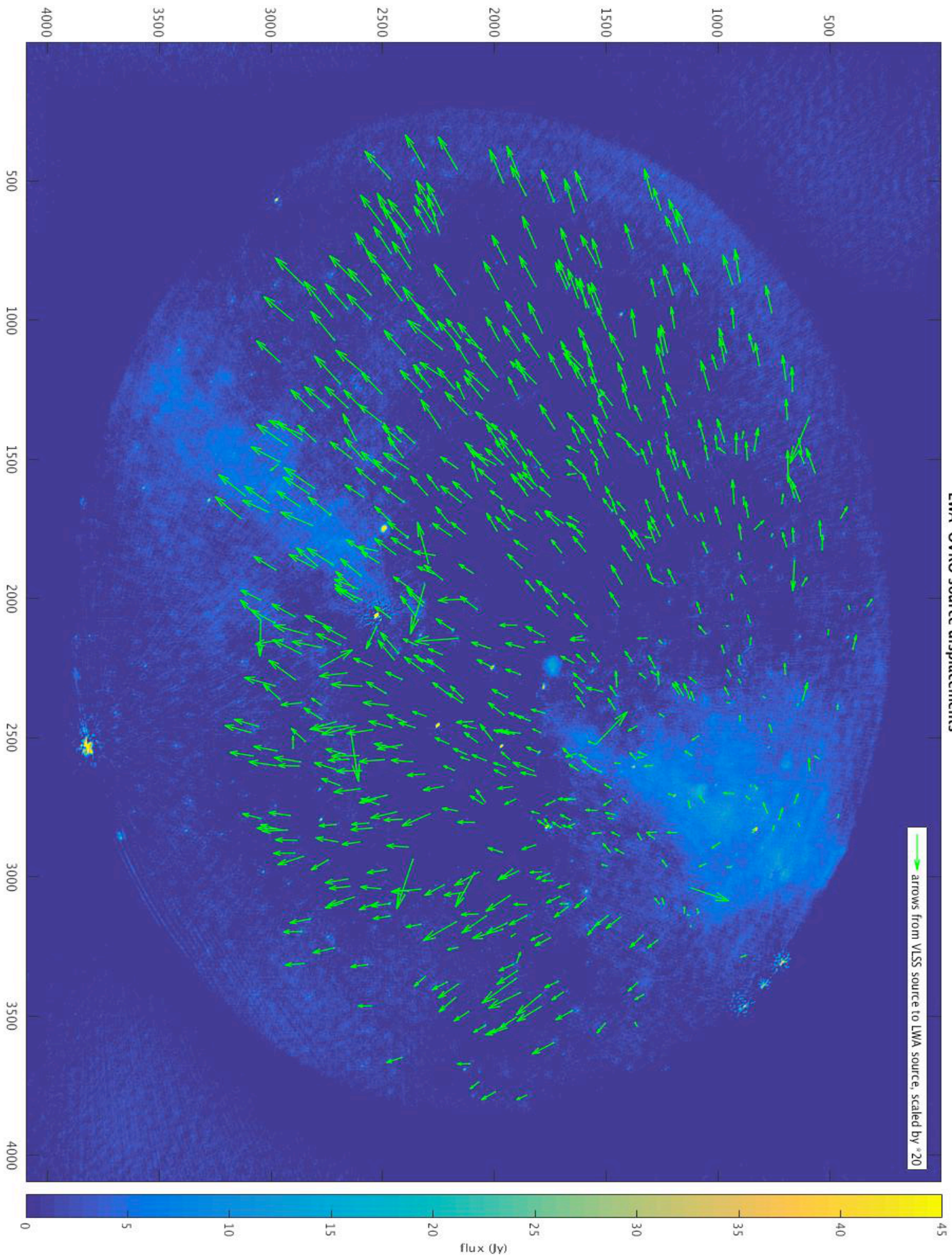
LWA-OVRO's Ionosphere Goals

- Ionospheric Science
 - Natural Hazard Detection
 - Strong focus of IARS group
 - Earthquakes; Tsunamis move ionosphere
 - Ionospheric waves can be detected before conventional methods
 - Serendipitous (eg. Plasma tubes)
- Radio-astronomical calibration

Point-source refraction map

- Long-baseline LWA can see many point sources
- Identify and compare positions to VLA sky survey (VLSS)
 - Image correction
 - All-sky ionosphere measurement
- Detection algorithm related to Lang et al. 2009

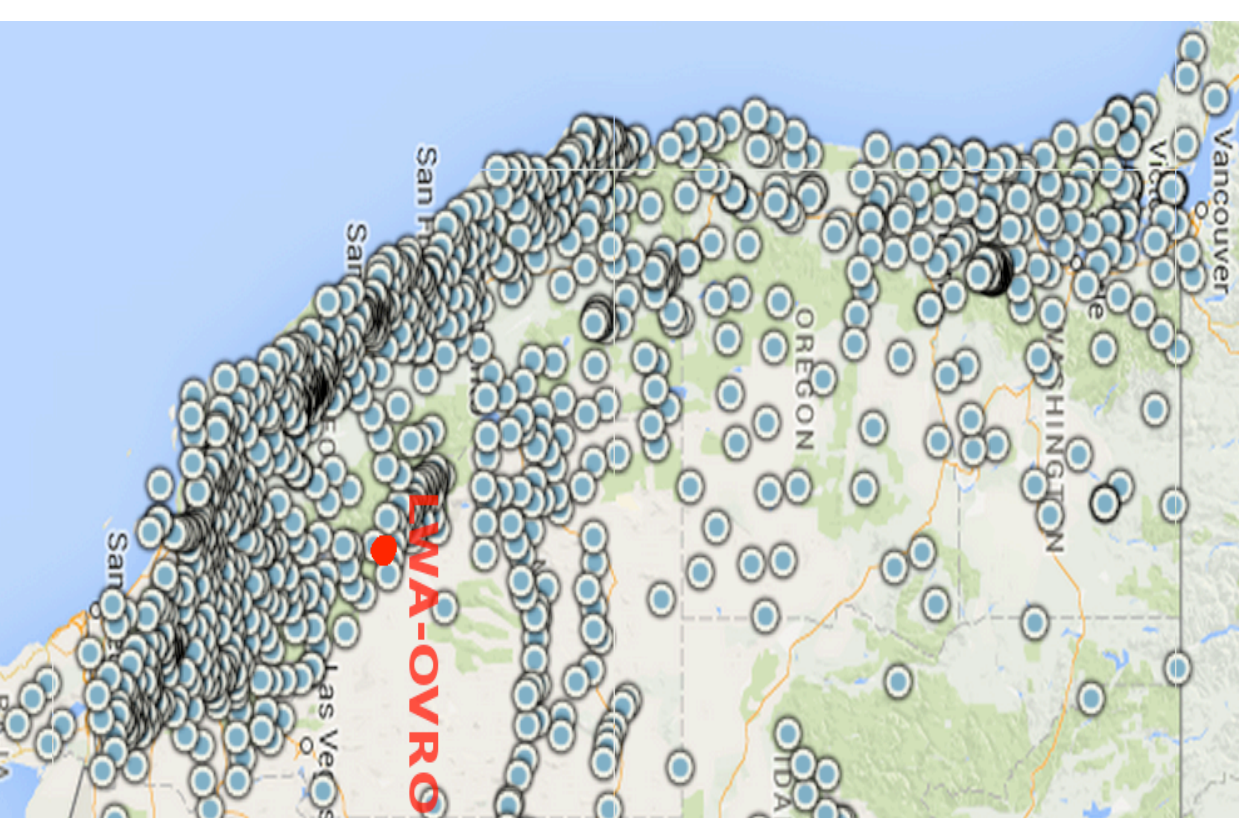
LWA-OVRO source displacements





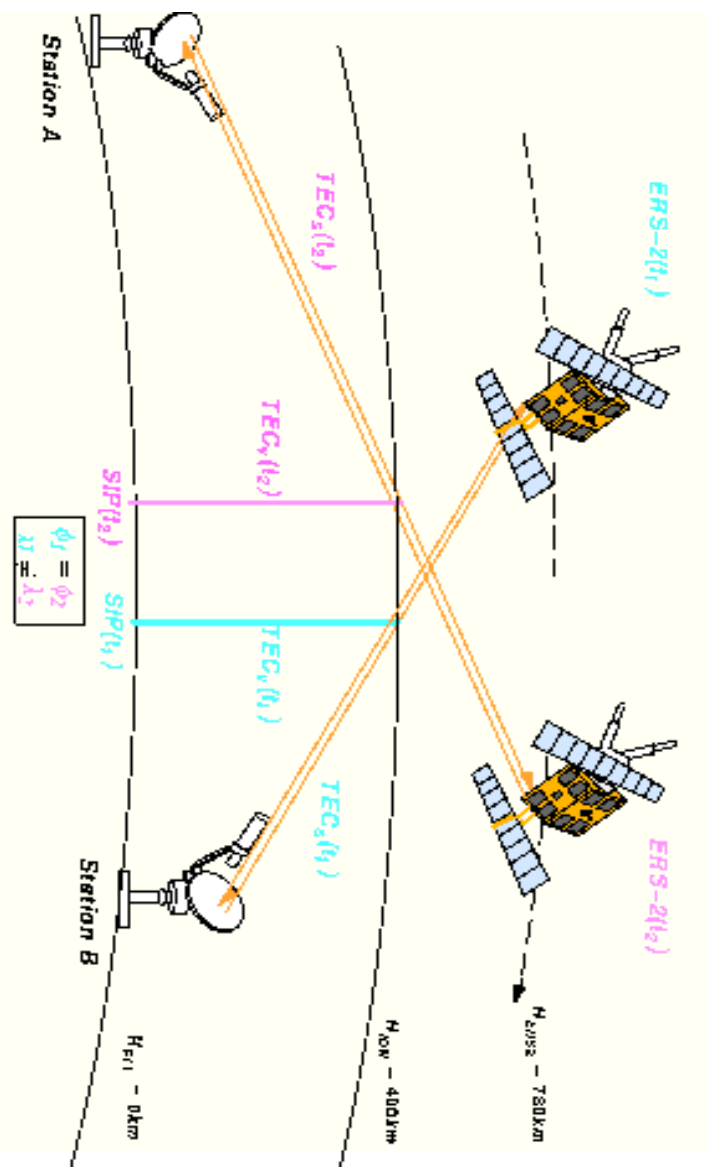
GPS Tomography (1)

- ~1400 GPS stations around California (for seismology)
- LWA-OVRO uniquely positioned for this (lucky!)
 - As long as you enjoy earthquakes.....



GPS Tomography (2)

- Global Ionospheric Model (GIM) provided by JPL IARS group
- Reconstruct 3d map of ionosphere density
- Ray-trace through map to estimate distortion



GPS Tomography Pipeline

- Raw data freely available
- Parsed by JPL packages (GIPSY, GIM)
 - Cycle-slip detection
 - Carrier phase->coarse leveling
 - Global satellite & receiver bias estimation
 - (one bias per receiver, satellite: ~1400 biases total)
- Product: (SOBS, VOBS, IPP location, Sat#, Receiver#, etc)



GPS Problems (1)

- Appears to be further systematic
 - Instead of satellite, receiver biases, appears to be pass-by-pass bias
- My answer: fit a new SOBS bias on a pass-by-pass basis
 - 70,000 variables -> 50,000,000 data-points



Conclusions

- *Very early work!*
- Great potential for all-sky ionosphere measurement / calibration

Thanks!

Questions?

Ryan Monroe

rmonroe@caltech.edu

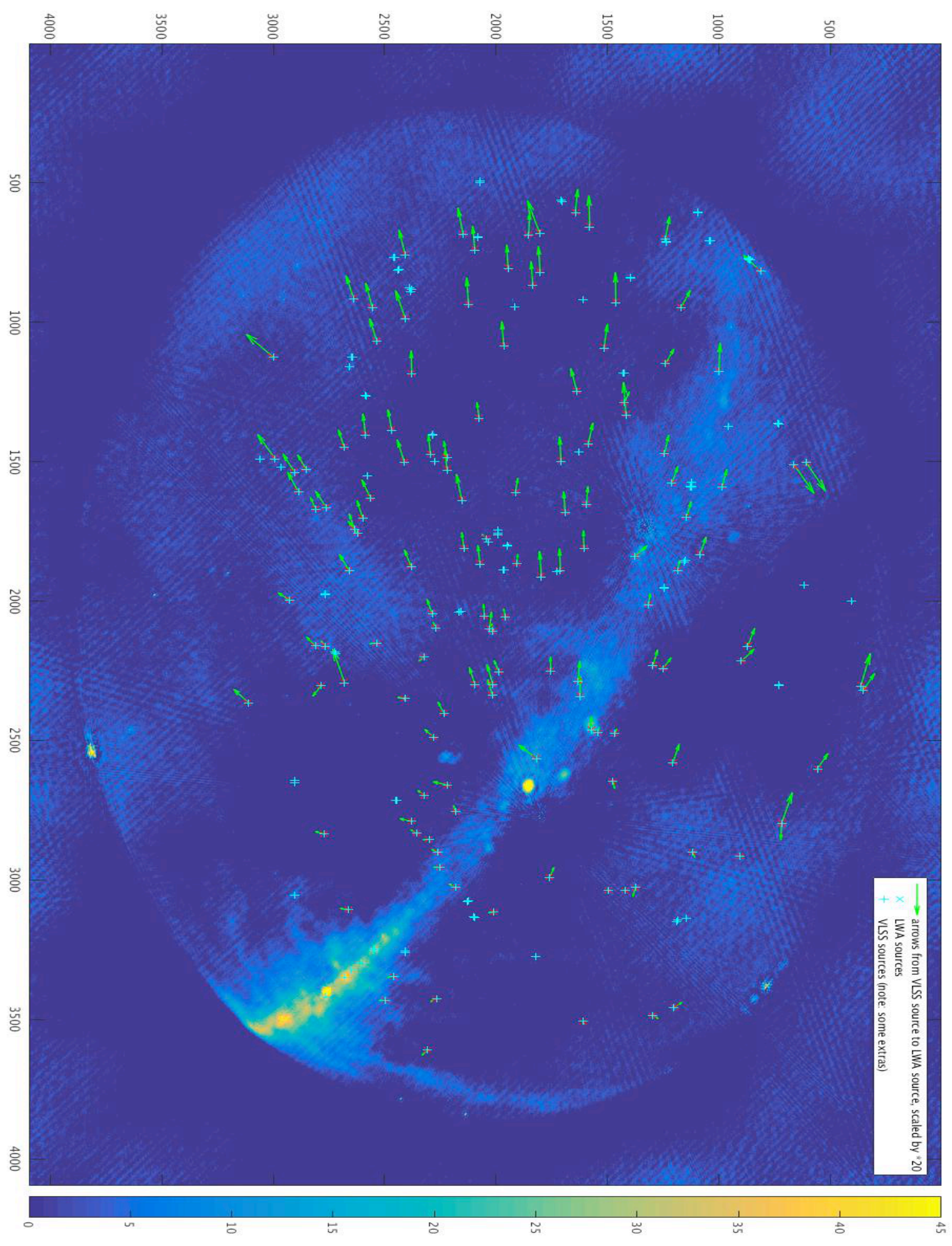
Backup slides/old plots

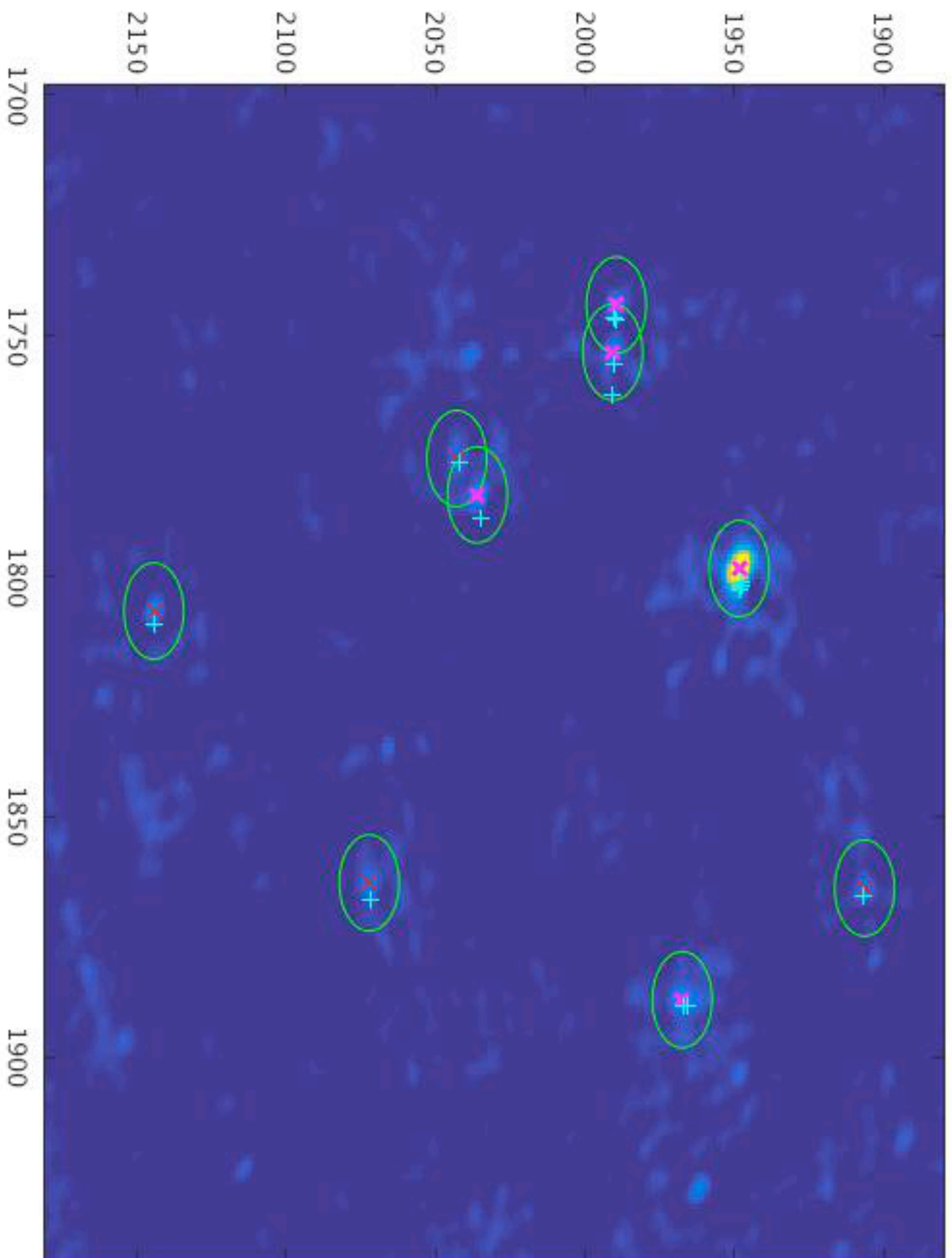
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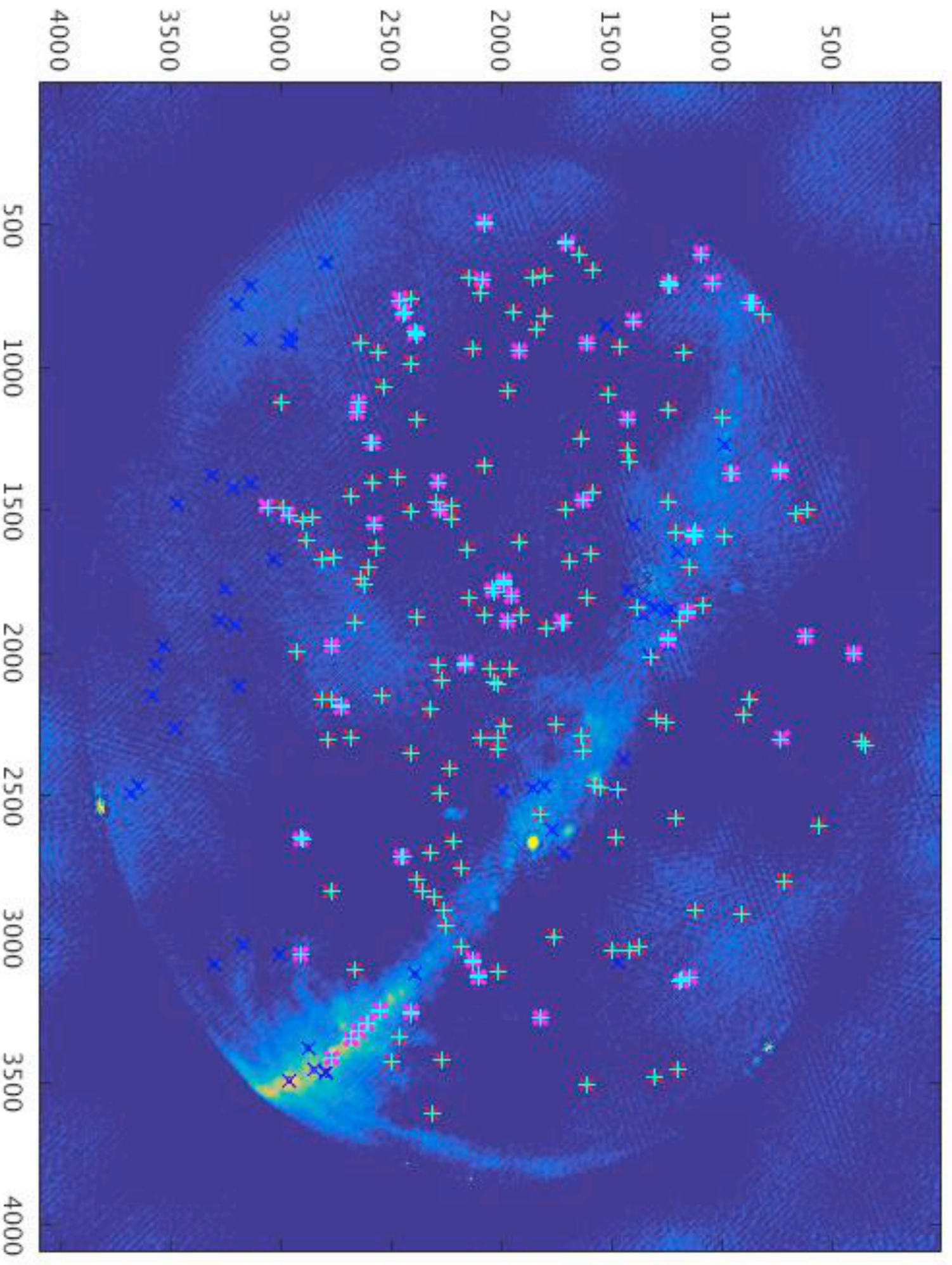
rmonroe@caltech.edu

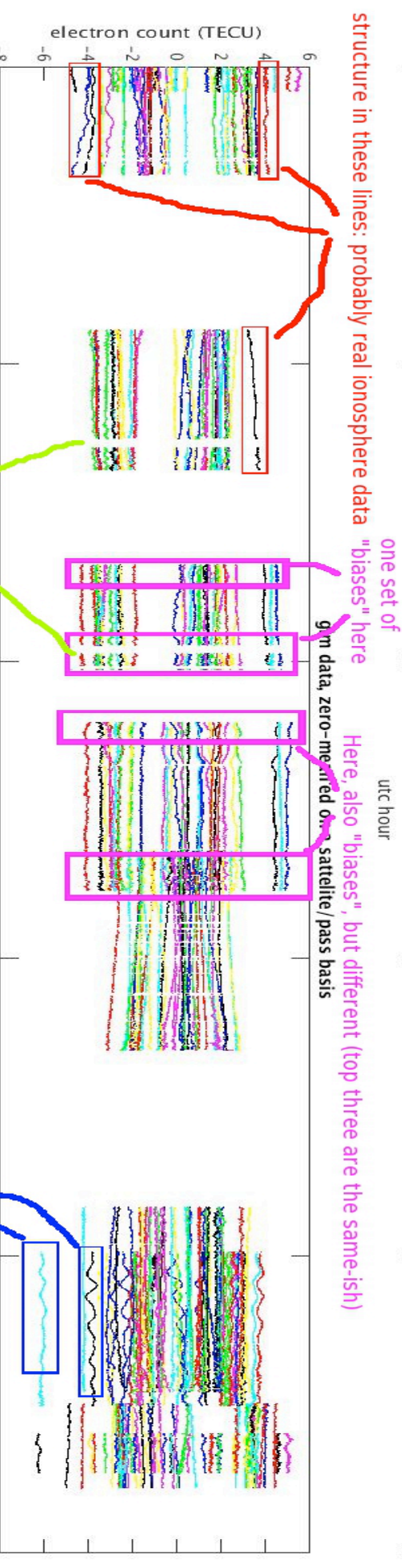
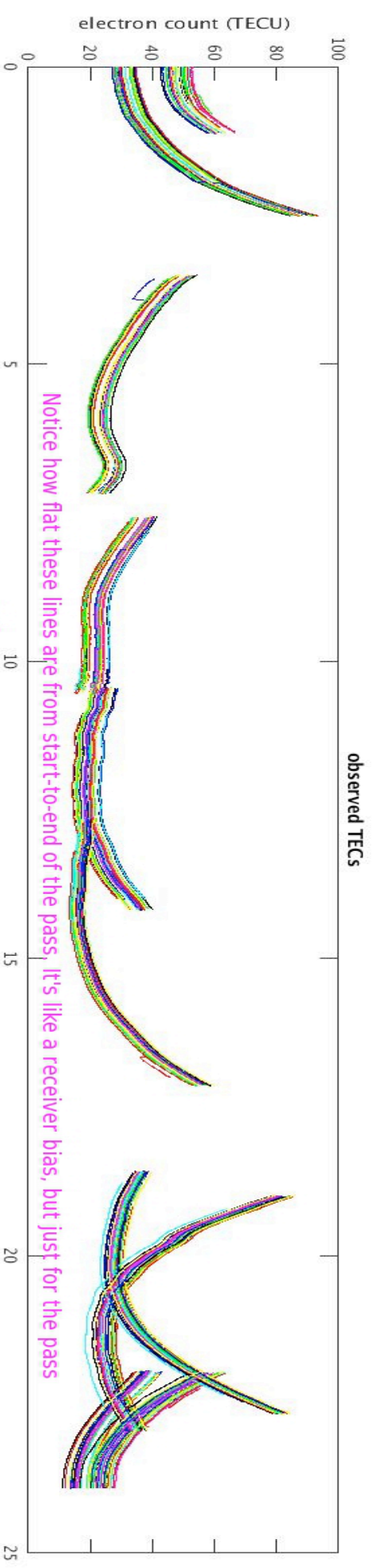
GPS Tomography (1)

- Direct measurements of Line-of-sight TECs using GPS
- Ideal Outcome:
 - 3d map of ionosphere
 - 20km resolution
 - ~3 vertical bases
 - <0.1 TECU accuracy









- BALD
- CA99
- DDMN
- DECH
- HOTK
- KNOL
- KRAC
- LINC
- MINS
- MWTP
- PE27
- PE28
- PE30
- PE31
- PE32
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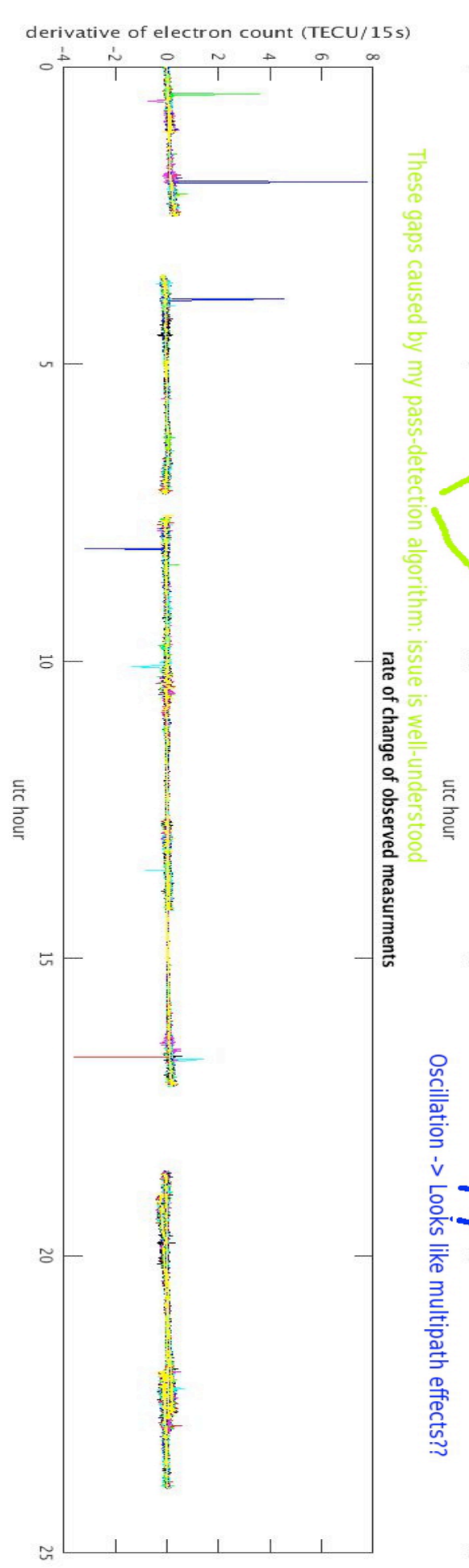


Figure 3

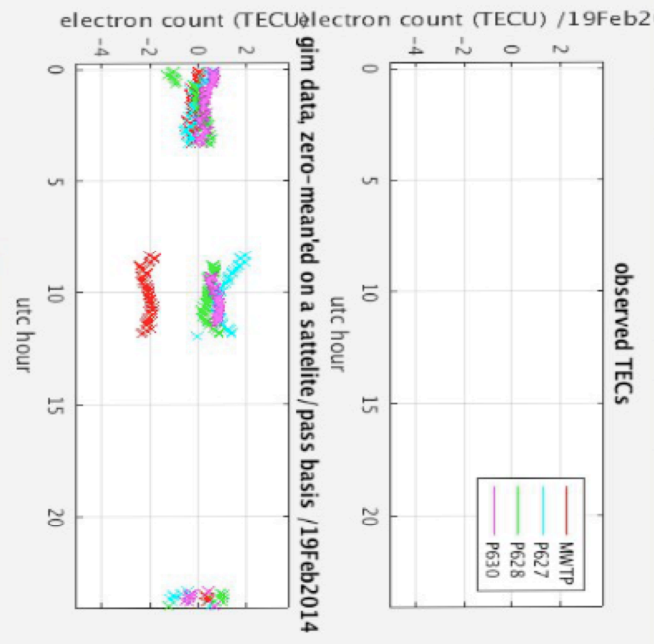


Figure 3

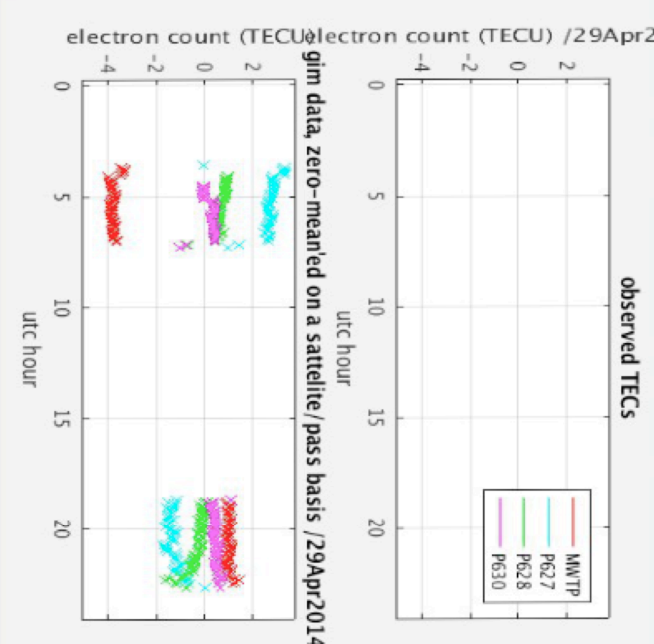


Figure 5

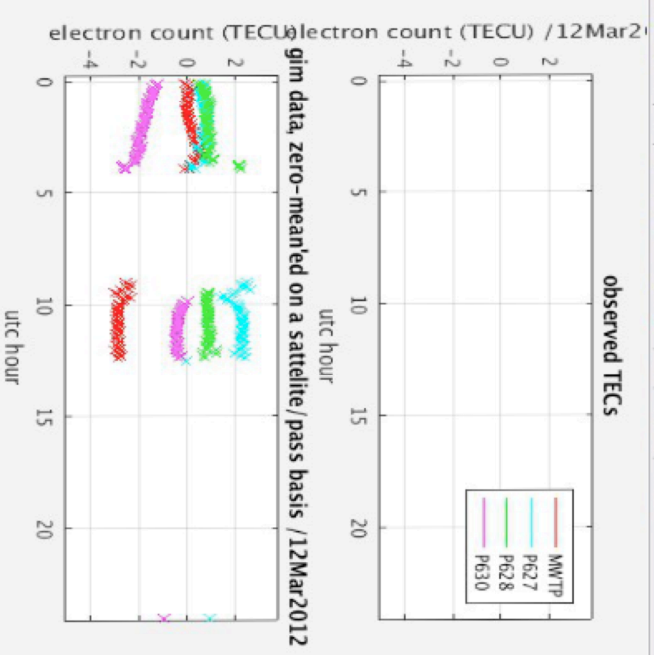


Figure 4

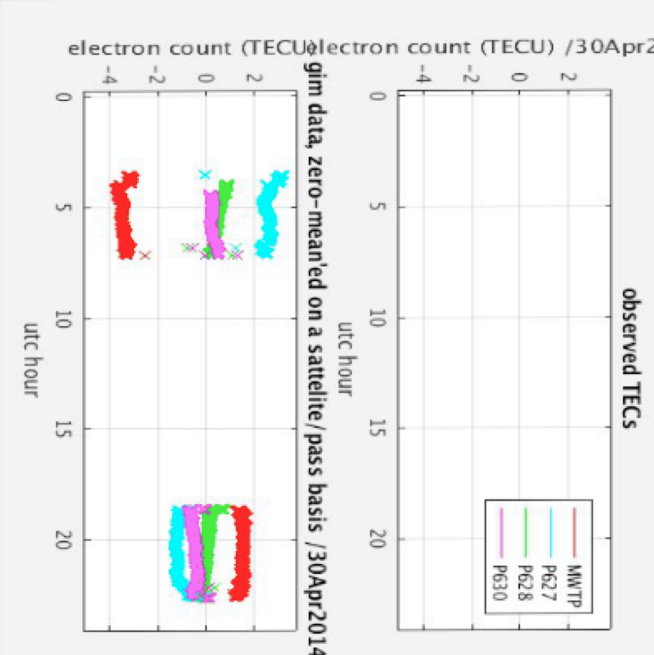


Figure 2

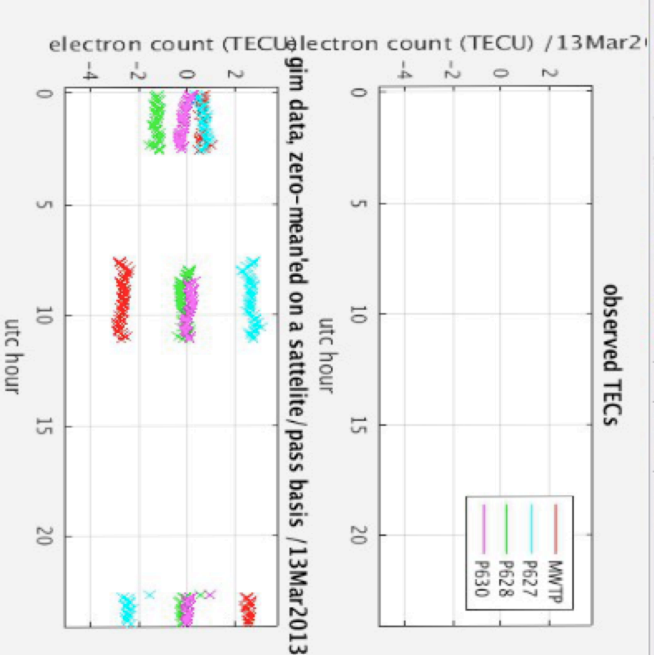
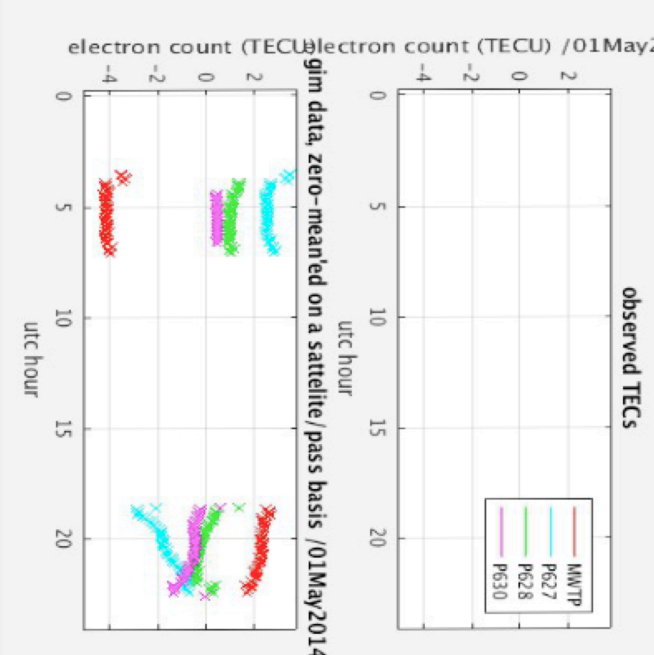
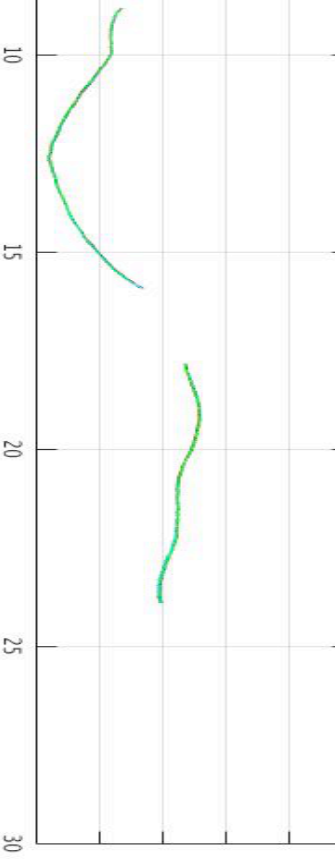
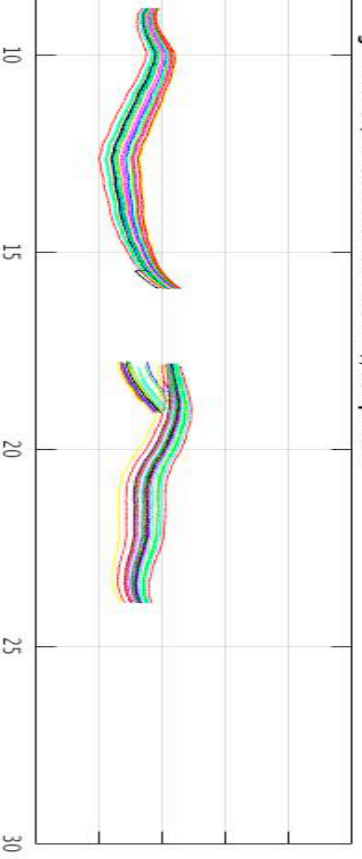


Figure 1

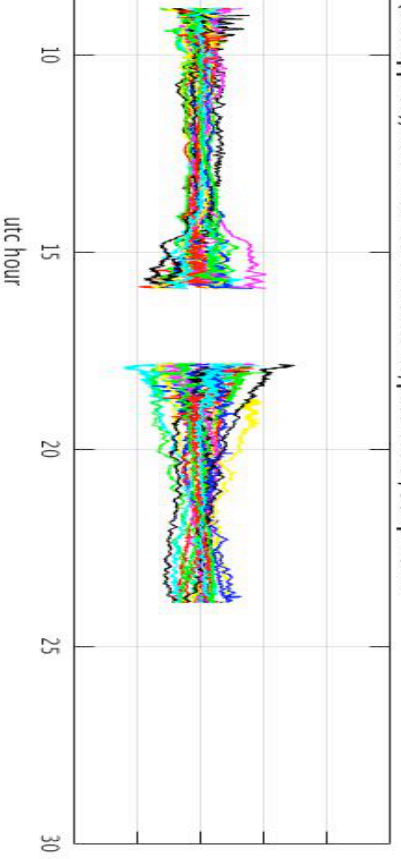




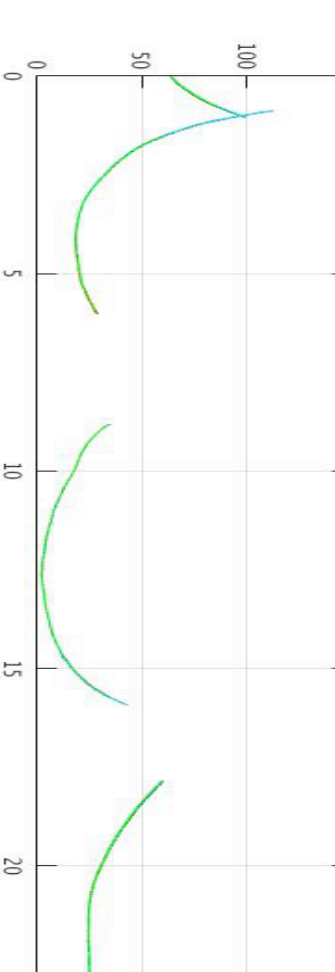
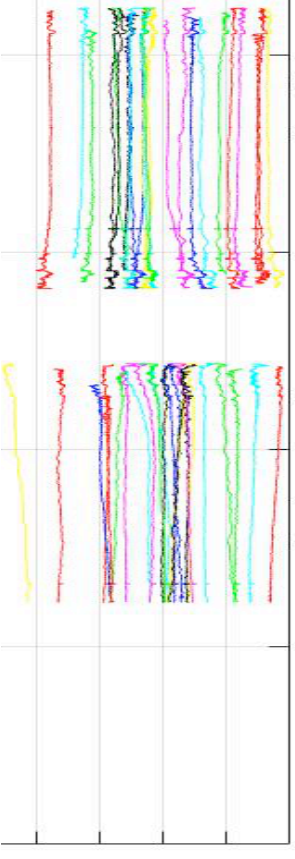
gim VOBS (FIT CORRECTION ABSENT) / 30Apr2014



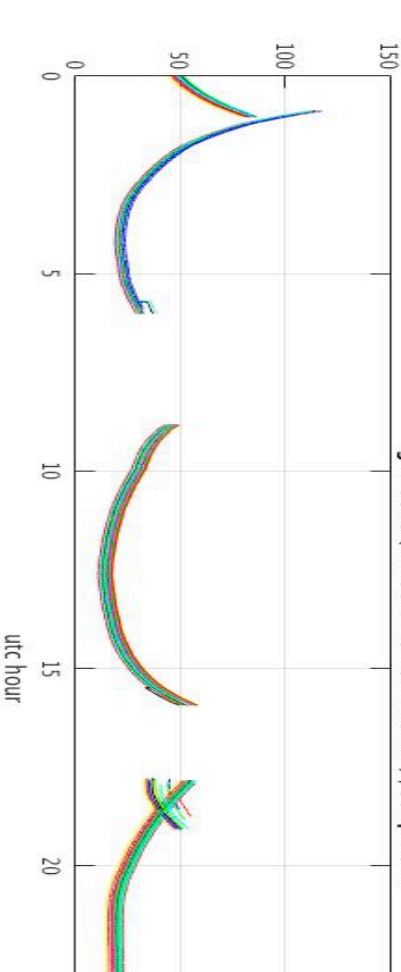
(bias applied), zero-meaned on a satellite/pass basis / 30Apr2014



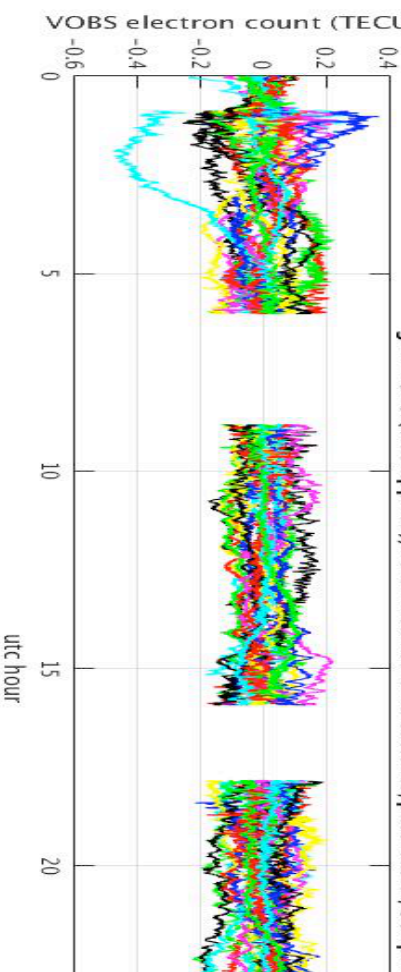
(no bias applied), zero-meaned on a satellite/pass basis / 30Apr2014



gim SOBS (FIT CORRECTION ABSENT) / 30Apr2014



gim SOBS (bias applied), zero-meaned on a satellite/pass basis / 30Apr2014



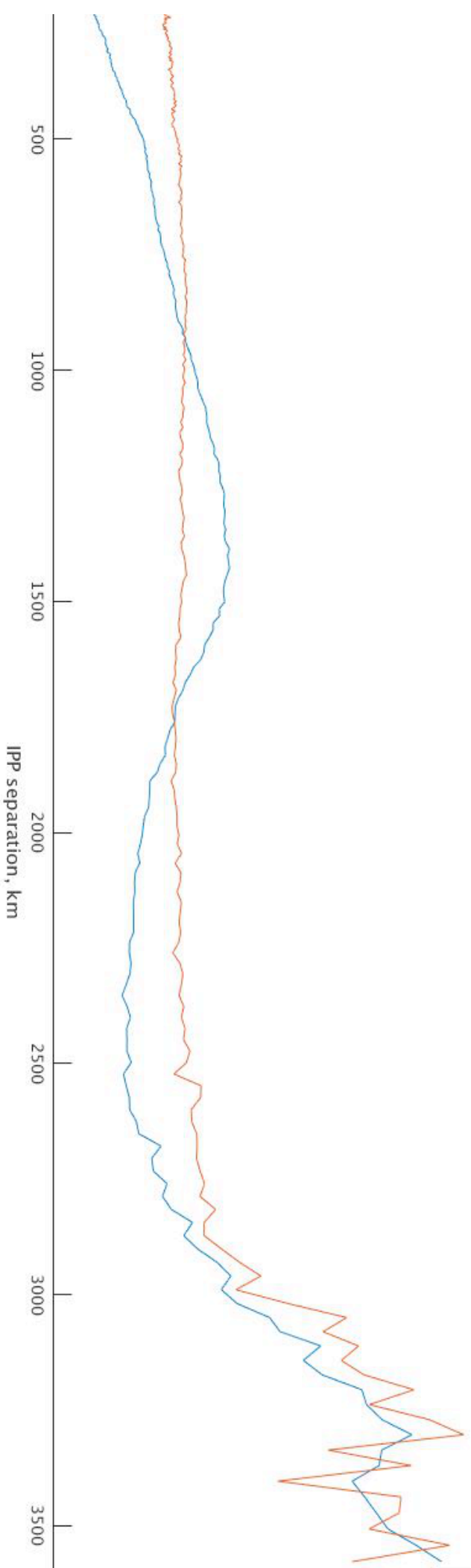
gim SOBS (no bias applied), zero-meaned on a satellite/pass basis / 30Apr2014



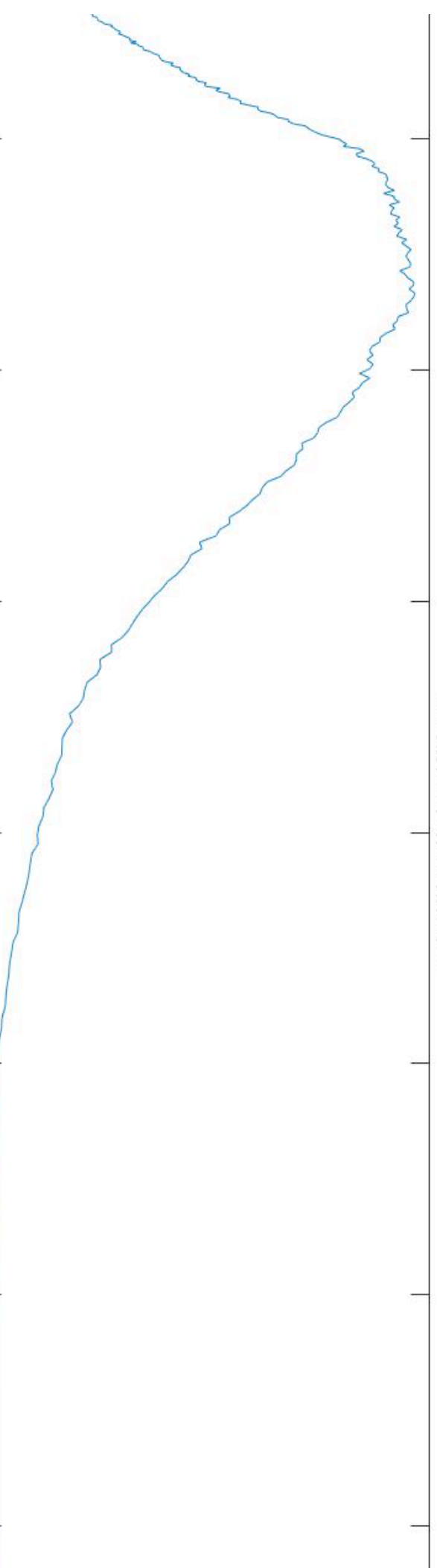
S electron count (TECU)

VOBS electron count (TECU)

Structure functions



#measurements in each bin



What is this fitting madness

- Observed bias clearly in SOBS measurements
- Since target measurement is VOBS, should be able to fit bias without totally ruining desired measurement
- Fit is very hard!
 - $70e3$ variables on $50e6$ data-points

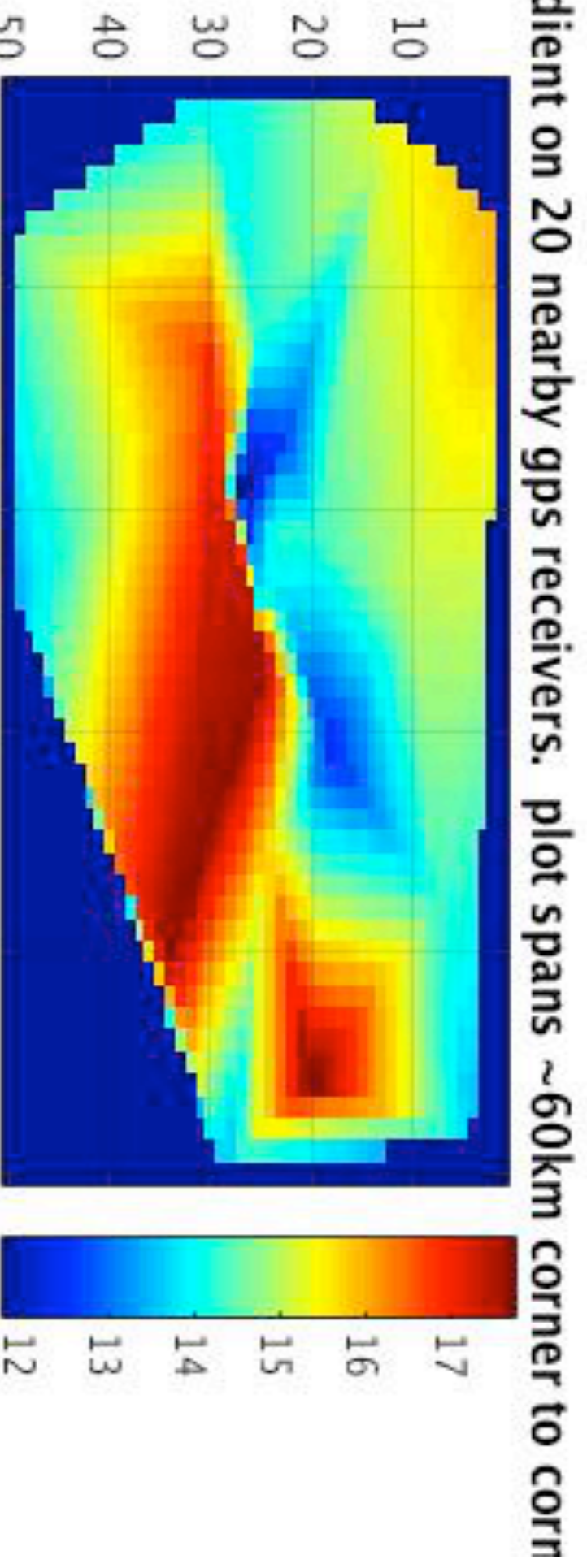
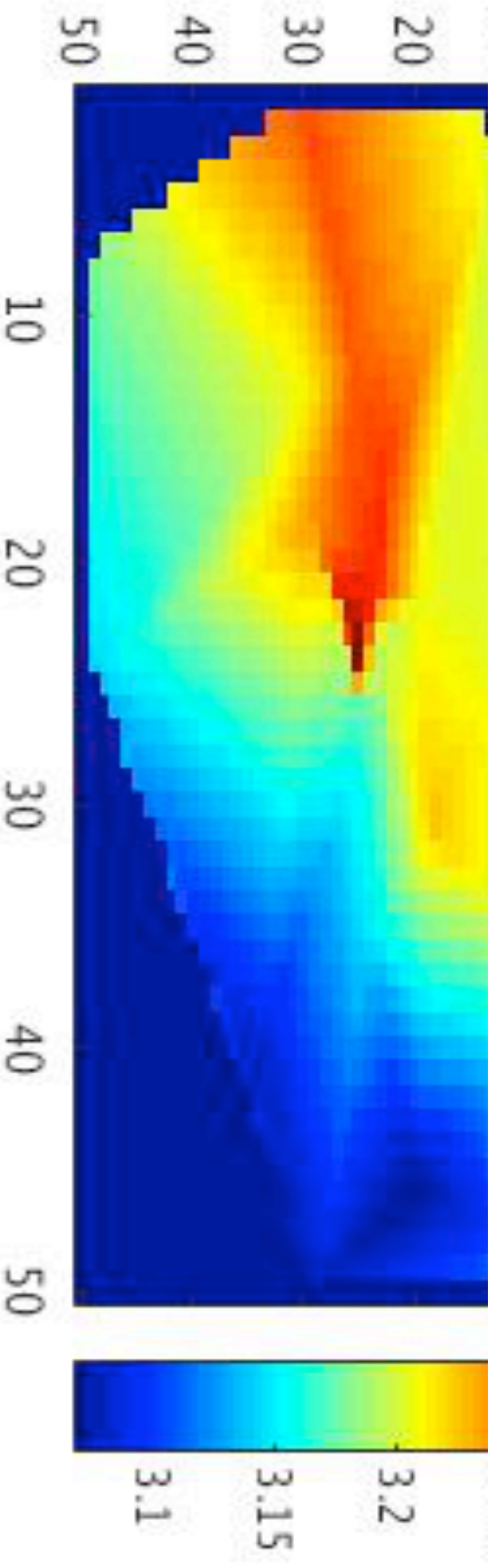
Definition of fit

- “IPPs which are nearby should have similar VOBS values”
- Minimize variance in (space, time) gridded VOBS by adjusting SOBS
- (put math here if I have time)

Fitting Challenges

- 50,000,000 measurements → 70,000 bias terms
- Extensive computational optimization necessary
- Massive cycle slips (bad GIPSY code?)
- VOBS estimate is only first order
 - Must filter error equations to include only measurements from nearby GPS receivers
- Need passes to have sufficient unique IPP gridding bins; need IPP gridding bins to have sufficient unique passes
 - Iterate filtering until convergence
- Need measure to all have minimum to reach other

Gradient map (fitted on top)

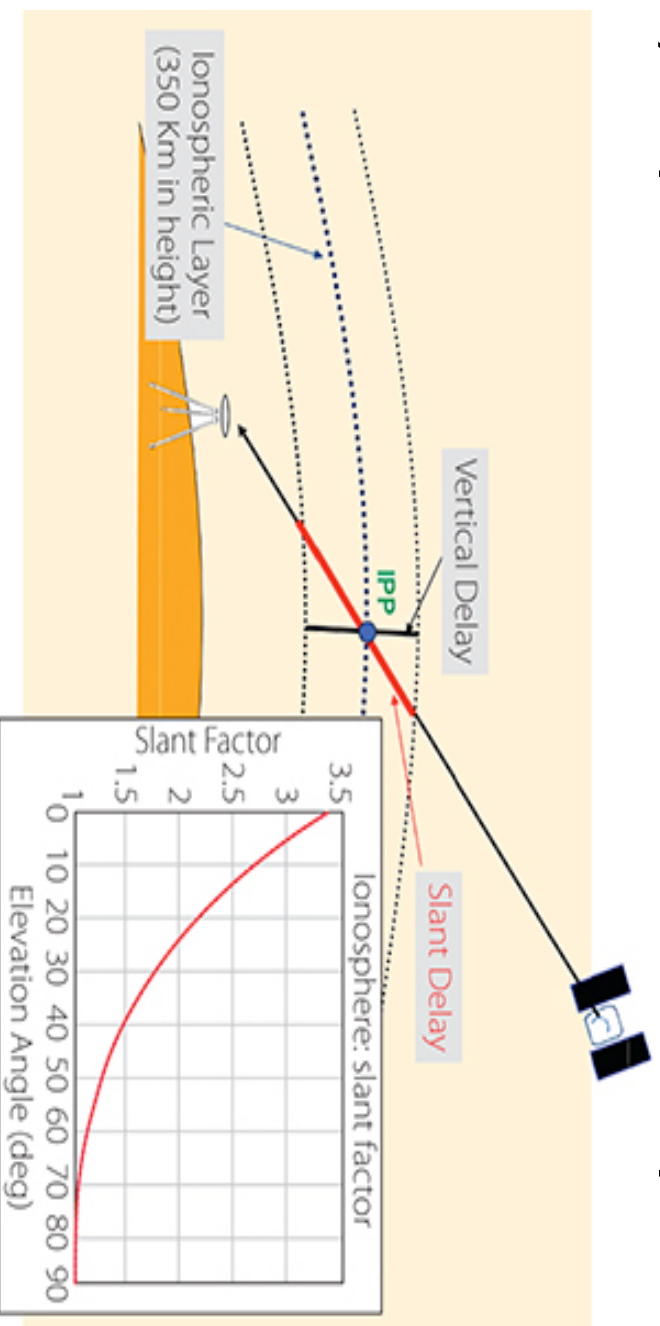


Structure functions

- Original GIM structure function is terrible! Does not decrease with decreasing distance
- Mine probably also bad: my structure function should be lower than original GIM at all distance scales
- Idea: poor coupling between IPPs of different satellites
 - Allows for bias drift in distant points' IPPs

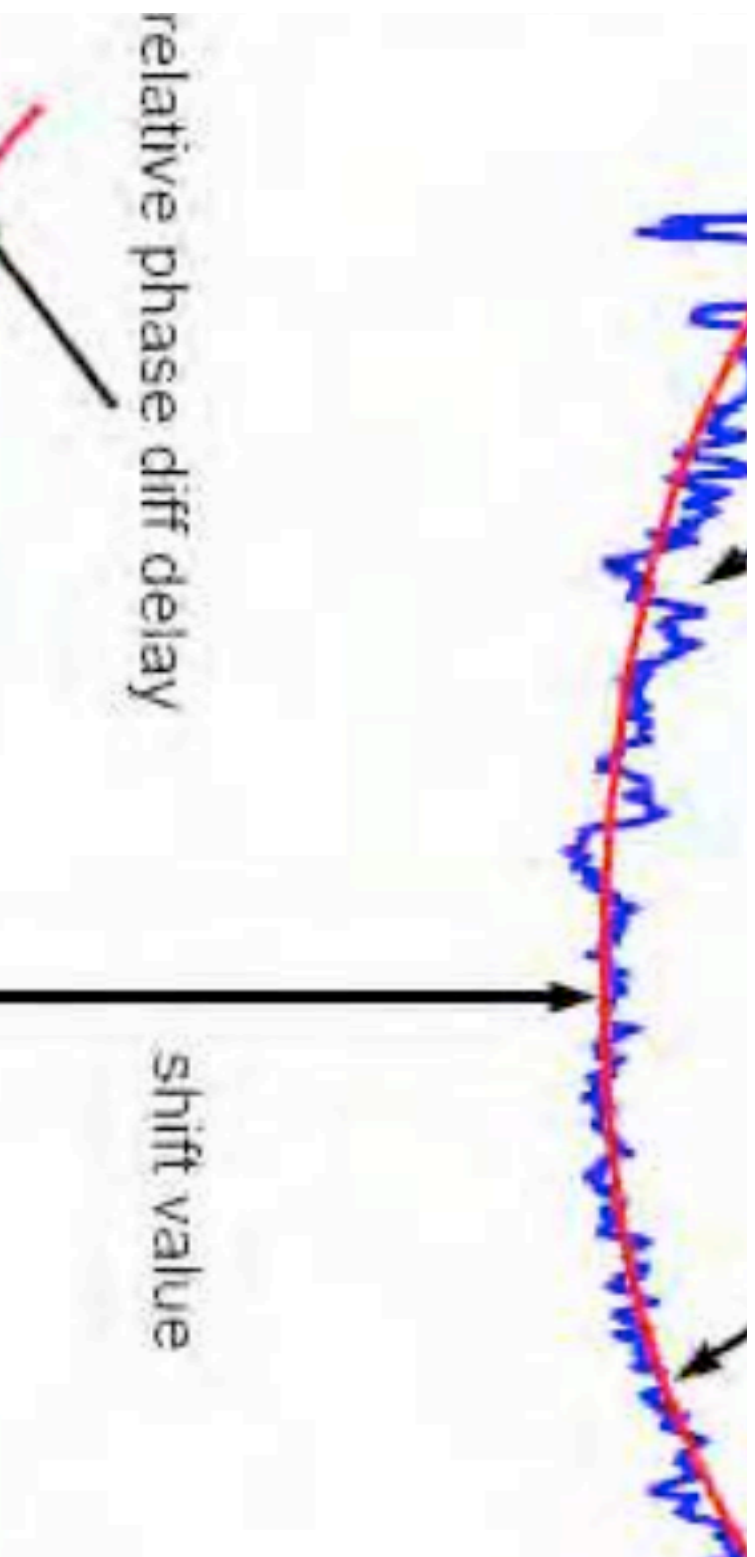
GPS Tomography (2)

- GPS Measurable: “Slant TEC” (SOBS / STEC)
 - Line-of-sight measurement from receiver to satellite
- Common approach: assume ionosphere is thin
 - Implies linear conversion to Vertical TEC (VOBS / VTEC) at point of intersection with ionosphere



GPS Tomography: sources of error

- Clock drift
- Inter-frequency bias
 - One per receiver and satellite
 - Phase leveling
 - Delay measurement noisy but absolute
 - Phase measurement clean but relative



GPS Problems (2)

-
- **Non-physical!** But the data doesn't lie
 - Previously undiscovered source of GPS ionosphere bias?
 - Receiver multipath?